

A Multi-Modal Auditory-Visual-Tactile e-Learning Framework

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This work is supported by the European Union through the Erasmus+ Program under Grant 2020-1-NO01-KA203-076540, project title "AugmentedWearEdu",
https://augmentedwearedu.uia.no/



Introduction

- E-Learning courses have been boosted by the Covid-19 pandemic;
- E-Learning brings several possibilities in terms of interactions for the students;

[1] Sanfilippo, F., Blažauskas, T., Salvietti, G., Ramos, I., Vert, S., Radianti, J., Majchrzak, T.A.: Integrating VR/AR with haptics into STEM education. In: Proc. of the 4th International Conference on Intelligent Technologies and Applications (INTAP 2021). Springer (2021), accepted for publication.



Motivation

- Wearable haptic devices that enable a multi contact interaction with virtual objects;
- Opportunity of new e-Learning contents that include tactile experience;
- Necessary to develop systems with a reduced cost by using commercially available offthe-shelf (COTS) components.



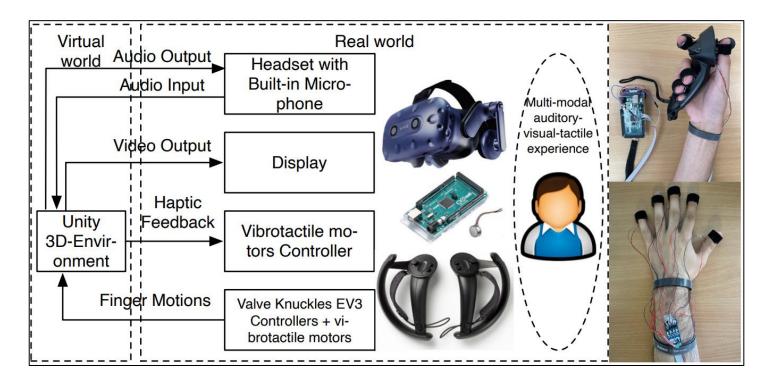




- [2] Facebook Technologies, LLC. "Oculus Touch". 2021. url: https://www.oculus.com/rift/
- [3] Valve Corporation. "Valve Index Controllers". 2021. url: https://store.steampowered.com/app/1059550/Valve_Index_Controllers/
- [4] HaptX Inc. "HaptX Gloves". 2021. url: https://haptx.com/

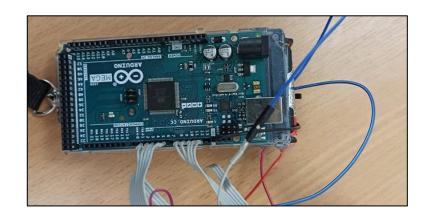


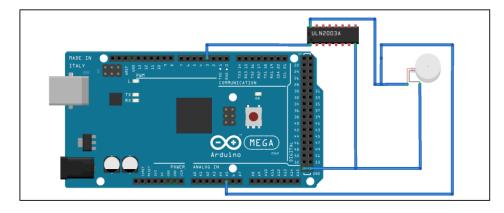
Framework architecture



Hardware implementation

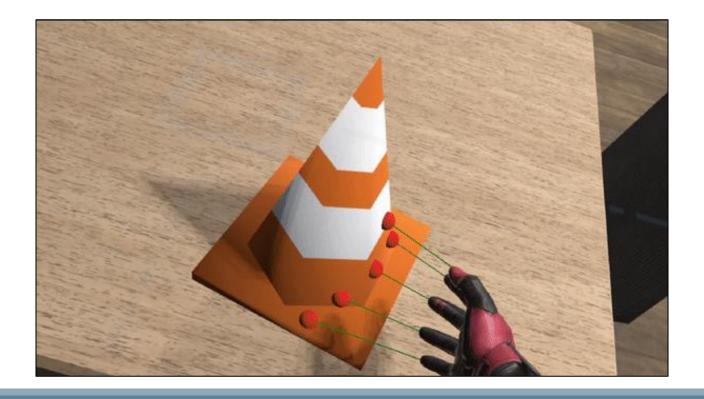








Rendering strategies







Equations

- Force calculation: $F_i = k(t d_i) k_v v_i$,
- · Vibration actuator: $D_i = \frac{\alpha F_i F_{min}}{F_{max} F_{min}}$,
- Pitch frequency: $f_i = f_{min} \frac{\beta(F_i F_{min})(f_{max} f_{min})}{F_{max} F_{min}}$,
- · Wavelength: $\lambda_i = f_{min} \frac{\gamma(F_i F_{min})(\lambda_{max} \lambda_{min})}{F_{max} F_{min}}$,

F - force:

k – stiffness:

 k_{v} – damping constants;

t – distance tolerance of contact;

d− distance value of contact;

 V_i – approaching velocity;

D – *vibration actuator;*

 α – scaling factor;

 F_{min} and F_{max} — minimum and maximum renderisable forces respectively;

f– pitch frequency

 β – scaling factor

 $f_{min} - f_{max}$ minimum and maximum renderisable pitch frequency

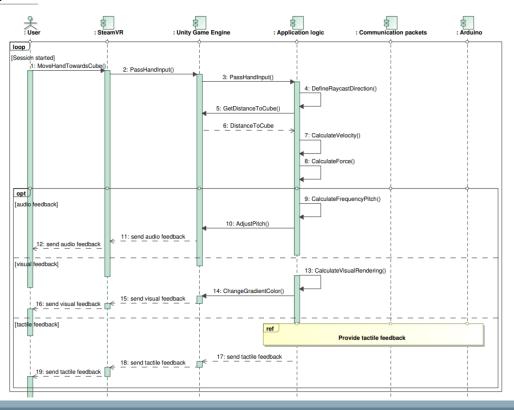
 λ – wavelength range (visible spectrum)

 γ – scaling factor

 $\lambda_{min} - \lambda_{max}$ minimum and maximum renderisable wavelength frequency

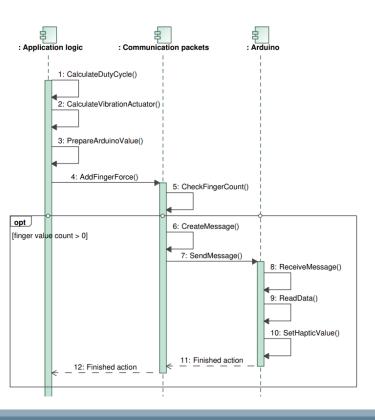
Interaction with virtual object





Tactile feedback rendering





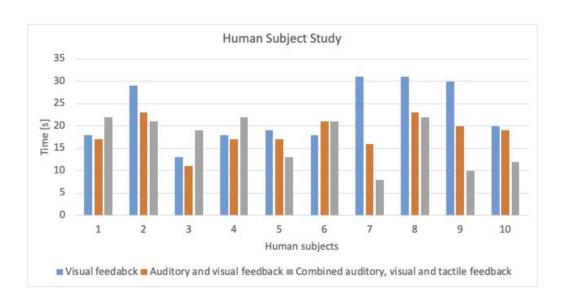


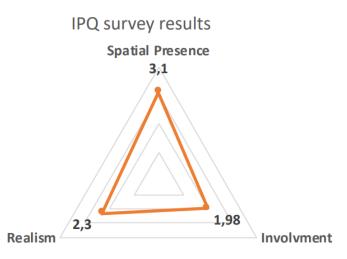
Human subject study





Experimental results





[5] Panahi, S.M., Fathi, A.A., Azad, F.P., Montazer, G.A.: Reliability and validity of igroup presence questionnaire (IPQ) (2009).

Conclusions and Future work



- Merge of virtual reality (VR) tools with a novel wearable haptic device and vibrotactile actuators helped in achieving the immersive learning experience;
- Conducted human subject research helped evaluate the developed framework;
- The framework could be used to develop teaching modules;







Thank you for your attention!

Do you have any questions?





References

- 1. Sanfilippo, F., Blažauskas, T., Salvietti, G., Ramos, I., Vert, S., Radianti, J., Majchrzak, T.A.: Integrating VR/AR with haptics into STEM education. In: Proc. of the 4th International Conference on Intelligent Technologies and Applications(INTAP 2021). Springer (2021), accepted for publication.
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- 5. Panahi, S.M., Fathi, A.A., Azad, F.P., Montazer, G.A.: Reliability and validity of igroup presence questionnaire (IPQ) (2009)